

# Technote 1

May 1991  
Revised 6/25/2008

## Equivalent Noise Bandwidth

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## Equivalent Noise Bandwidth

Given a system with a transfer function  $H(j\omega)$ , the equivalent noise bandwidth is defined by:

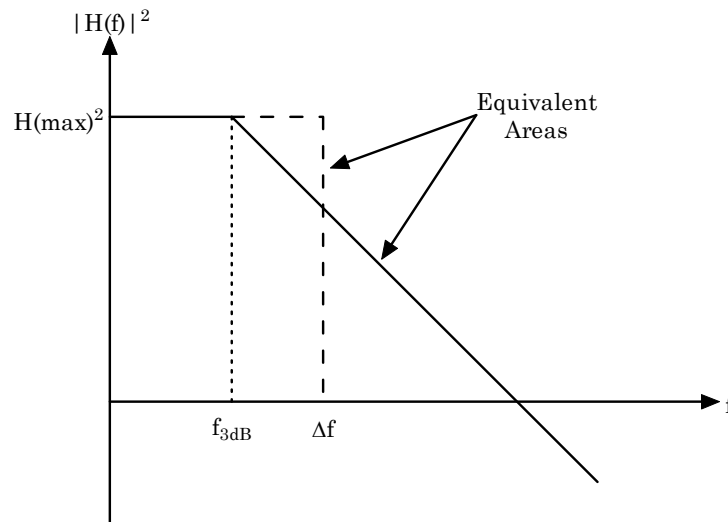
$$\Delta f = \frac{1}{2\pi} \int_0^{\infty} \left| \frac{H(j\omega)}{H(\max)} \right|^2 d\omega \quad (1)$$

Where:

$H(\max)$  is the maximum value of the transfer function  $H(j\omega)$

$\Delta f$  is the equivalent noise bandwidth (NBW)

This corresponds to a “brickwall” filter of bandwidth  $\Delta f$  and a noise power equivalent to the original transfer function. Stated more simply, the NBW is the frequency such that a rectangle defined by  $H(\max)^2$  and  $\Delta f$  has an area equal to the area under  $|H(\omega)|^2$ . This is illustrated in Figure 1.



*Figure 1. Illustration of Equivalent Noise Bandwidth*

The relationship between  $\Delta f$  and  $f_{3dB}$ , the 3dB frequency of the system, depends on the number of poles in the transfer function. Typically, a single pole rolloff (or dominant pole rolloff) is assumed. For higher order systems,  $\Delta f$  will approach  $f_{3dB}$  as shown in Table 1.

Number of poles	Rolloff dB/Decade	Equivalent Noise Bandwidth $\Delta f$
1	-20	$1.57 f_{3dB}$
2	-40	$1.22 f_{3dB}$
3	-60	$1.15 f_{3dB}$
4	-80	$1.13 f_{3dB}$
5	-100	$1.11 f_{3dB}$

*Table 1. Noise Bandwidth as a function of the number of poles in the system response*

Using  $1.57f_{3dB}$  in all calculations does not introduce a large error for 2<sup>nd</sup> or 3<sup>rd</sup> order systems since the noise is typically a function of  $\Delta f^{1/2}$ . Use caution if the transfer function exhibits gain peaking at high frequencies as this will result in underestimating system noise.

The noise bandwidth for a single pole (-20dB/decade) rolloff is computed as follows:

$$H(\omega) = \frac{1}{1 + j \frac{\omega}{\omega_{3dB}}} \quad (2)$$

$$|H(\omega)| = \frac{1}{\sqrt{1 + \frac{\omega^2}{\omega_{3dB}^2}}} = \frac{\omega_{3dB}}{\sqrt{\omega_{3dB}^2 + \omega^2}} \quad (3)$$

Note that  $H(max) = 1$

$$\Delta f = \frac{1}{2\pi} \int_0^{\infty} \frac{\omega_{3dB}^2}{\omega_{3dB}^2 + \omega^2} d\omega = \frac{\omega_{3dB}^2}{2\pi} \frac{1}{\omega_{3dB}} \tan^{-1} \left( \frac{\omega}{\omega_{3dB}} \right) \Bigg|_0^{\infty} \quad (4)$$

$$\Delta f = \frac{\pi}{2} \frac{\omega_{3dB}}{2\pi} \quad (5)$$

$$\boxed{\Delta f = \frac{\pi}{2} f_{3dB}} \quad (6)$$

What if you have a bandpass filter<sup>1</sup>? The math gets a little ugly if you want to start with Equation (1) and I will leave the analysis to you. I have verified that the result is the same as above with the filter bandwidth substituted in place of the 3 dB frequency.

$$\boxed{\Delta f = \frac{\pi}{2} (f_h - f_l) = \frac{\pi}{2} f_{BW}} \quad (7)$$

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<sup>1</sup> Keep in mind there is, practically speaking, no such thing as a highpass filter as any circuit will eventually run out of bandwidth due to design or the interaction of parasitics.